

**Vivekananda College of Engineering & Technology, Puttur**  
 [A Unit of Vivekananda Vidyavardhaka Sangha Puttur ®]  
 Affiliated to VTU, Belagavi & Approved by AICTE New Delhi

CRM08

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**CONTINUOUS INTERNAL EVALUATION - 2**

Dept: ECE	Sem / Div: IV	Sub: Signals and Systems	S Code: 18EC45
Date: 05/08/22	Time: 9:30-11:00am	Max Marks: 50	Elective: N

Note: Answer any 2 full questions, choosing one full question from each part.

QN	Questions	Marks	RBT	CO's
<b>PART A</b>				
1 a	Show that the step response of an LTI system is running integral of impulse response and also prove distributive property of convolution integral.	9	L2	CO2
b	Determine whether the following systems represented by impulse responses are stable and causal: (i) $h[n] = u[n - 1] - u[n - 5]$ (ii) $h[n] = 0.5^{ n }$ (iii) $h(t) = e^{-t}u(-t)$ iv) $h(t) = u(t - 1)$	8	L3	CO2
c	What is Region of Convergence (ROC) of Z-Transform? Mention its properties with examples.	8	L2	CO4
<b>OR</b>				
2 a	State and prove distributive and associative property of convolution sum.	9	L2	CO2
b	Evaluate the step response for the LTI system represented by the following impulse responses. i) $h(t) = e^{-td}$ ii) $h[n] = \left(\frac{1}{2}\right)^n u[n-2]$	8	L3	CO2
c	Find the z-transform by using appropriate properties. i) $x[n] = n \sin\left(\frac{\pi}{2}n\right) u[-n]$	8	L3	CO4

		ii) $x[n] = (n-2)\left(\frac{1}{4}\right)^n u[n-2]$			
		<b>PART B</b>			
3	a	Find the time domain signal corresponding the following Z-transform, $X(z) = \frac{(0.25z^{-1})}{((1-0.5z^{-1})(1-0.25z^{-1}))}$ with the ROCs i) $0.25 <  z  < 0.5$ ii) $ z  < 0.25$ iii) $ z  > 0.5$	9	L3	CO4
	b	State and prove the following properties of Z-transform: (i) Time-reversal (ii) Convolution	8	L2	CO4
		Using power series expansion method determine the inverse z-transform of I) $X(z) = e^{z^2}$ ii) $X(z) = \frac{1}{1 + \frac{1}{2}z^{-1}}$ ROC $ z  > 0.5$	8	L2	CO4
<b>OR</b>					
4	a	A discrete LTI system is characterized by following Difference equation: $y[n] = y[n-1] + y[n-2] + x[n-1]$ i) Find the system function. ii) Indicate ROC if system is stable. iii) Indicate ROC if system is causal. iv) Obtain impulse response in both cases.	9	L3	CO4
	b	The z-transform of a sequence is given by, $X(z) = \frac{(z(z^2 - 4z + 5))}{((z-1)(z-2)(z-3))}$ find $x(n)$ for the following ROCs, i) $2 <  z  < 3$ ii) $ z  > 3$	8	L3	CO4
	c	Find the Z-transform and sketch the ROC, poles and zeroes in the Z-plane. $x[n] = 0.5^n u[n] + 2^n u[-n - 1]$	8	L2	CO4